

# Performance Investigation of a Savonius Wind Turbine with Unconventional Blade Designs Inspired by Sand Eels

Islam HASHEM<sup>\*12</sup>, Emeel KERIKOUS<sup>12</sup>, Stefan HOERNER<sup>1</sup>, Dominique THÉVENIN<sup>1</sup>

 <sup>1</sup> Laboratory of Fluid Dynamics and Technical Flows, Otto von Guericke University Magdeburg, 39106 Magdeburg, Germany.
<sup>2</sup> Mechanical Power Engineering Department, Faculty of Engineering-Mattaria, Helwan University, 11718 Cairo, Egypt. \*Corresponding Author. E-mail: islam.hashem@ovgu.de

## ABSTRACT

Wind turbines allow us to harness the power of the wind and turn it into mechanical energy. When the wind blows, the rotor blades spin, capturing available energy from the wind. Out of many kinds of wind turbines, efforts have been made here to improve the performance of Savonius turbines. The main drawback of such a turbine is its low efficiency. In the present study, a Savonius rotor with unconventional blade designs inspired biologically by sand eels has been proposed; aiming to improve its performance in terms of the output power coefficient  $(C_P)$ . Sand eels are small elongated sea fish and can frequently be found in shallow water. Two main geometrical parameters have been considered and normalized by the blade diameter (d); the maximum camber  $(f_{max})$  and the maximum camber location  $(X_{f_{max}})$ ; whereas the maximum thickness  $(t_{max})$ is kept as 20% of the maximum camber value to resemble the shape of a sand eel. A total of 54 blade designs have been evaluated using 2D numerical simulations to determine the aerodynamic behaviour of the new bio-inspired design. By comparison between th erotor with semi-circular arc blades and that with sand eel-like blades ( $f_{max}/d = 0.4$  and  $X_{f_{max}}/d = 0.8$ ), a noticeable improvement in the performance (up to 8.3% at  $\lambda = 0.8$ ) can be obtained in this manner.

Keywords: Bio-inspiration, CFD, performance, sand eels, Savonius rotor

# NOMENCLATURE

$C_P$	[-]	Power coefficient
$C_Q$	[-]	Torque coefficient
$f_{max}$	[m]	Maximum camber
$t_{max}$	[m]	Maximum thickness
$X_{f_{max}}$	[m]	Maximum camber location
$\theta$	[°]	Azimuth angle
λ	[-]	Tip speed ratio
Ω	[1/s]	Angular speed

#### **1. INTRODUCTION**

Due to the global energy crisis, research and development activities in the field of renewable energy, particularly wind energy, have increased significantly in many nations in recent years. Wind turbines are well-known devices for harvesting available energy from the wind and transform it into mechanical energy. Wind turbines are mainly classified into horizontal axis wind turbines (HAWTs) and vertical axis wind turbines (VAWTs). Horizontal axis wind turbines (HAWTs) are currently the most common type of wind turbines used for power generation. However, the performance of these turbines is limited due to the need for orientation mechanism (yaw), high installation cost, and the need for highspeed wind. Therefore, vertical axis wind turbines (VAWTs) have recently gained importance as a suitable alternative for energy production in residential and isolated places with low-speed wind. Vertical axis wind turbines (VAWTs) are divided into two basic types, Darrieus-type and Savonius-type rotors (Figure 1). The Darrieus-type VAWT was patented by the French engineer J. M. Darrieus in 1931 [1]. In principle, it consists of two curved blades with airfoil cross-section profile that generate aerodynamic lift, when the wind passes over its surface, as shown in Figure 1(a). The Savonius-type VAWT was invented by J. Savonius in 1929 [2]. The Savonius turbine is mainly a drag-driven VAWT and consists in its original design of two semi-circular buckets attached to a rotating shaft in opposing directions, as shown in Figure 1(b). Savonius wind turbines are commonly used owing to the simple design of its blades. Moreover, they are characterized by capability of self-starting, ability to capture wind from any direction, low manufacturing and maintenance costs, robustness and low cut-in speed. However, Savonius wind turbines have poor efficiency (less than 25%) compared to other types of wind turbines. Therefore, many researchers have tried to modify blade design and geometical parameters of the Savonius rotors,



Figure 1. A schematic of vertical axis wind turbines (VAWTs): (a) Darrieus-type and (b) Savonius-type

aiming to increase its efficiency. Some important works from the literature about unconventional blade designs to improve the performance of Savonius rotors are reported in Table 1.

# 2. PURPOSE OF THE PRESENT STUDY

Sand eels, also known as sand lances, are small, slender eel-like fish that grow to be approximately 9 inches long and often live in vast shoals. An analogy between sand eels and bio-inspired blades suggested for Savonius wind turbines is shown in Figure 2. However, while keeping the general geometrical ratios analog to a sand-eel shape (Figure 2(a)) the particular geometry, such as curvature should be adjusted for improved aerodynamics. For this purpose, two main geometrical parameters of the sandeel inspired blade (Figure 2(b)) have been considered and normalized by the blade diameter (d); the maximum camber  $(f_{max})$  and the maximum camber location  $(X_{f_{max}})$ ; whereas the maximum thickness  $(t_{max})$  is kept as 20% of the maximum camber value to remain in geometric ratios of a sand eel. In this way, a total of 54 sand eel-like blades have been generated and investigated as Savonius wind turbine to increase the turbine performance, as depicted in Figure 3. This is the focus of the present study.

## 3. METHODOLOGY

Savonius rotors typically consist of two semicircular arc blades, namely advancing blade (Blade A) and returning blade (Blade R). Figure 4 shows the geometrical parameters of a standard Savonius rotor as described by Hayashi et al. [12] in their experiment. *D* is the rotor diameter, *H* is the rotor height, *S* is the rotor overlap, *d* is the blade diameter and *a* is the shaft diameter. The azimuth angle ( $\theta$ ) is 0 when the chord line is parallel to the wind direction  $U_0$ . The length along the circular arc (*l*) is calculated



Figure 2. Analogy between sand eels (a) and bioinspired blades (b) suggested for a Savonius rotor

as  $\pi/2$ . The coordinate *s* is defined along the circular arc so that s/l is 0 and 1 at leading edge and trailing edge, respectively. The specifications of the tested rotor and its main dimensions are listed in Table 2.

By referring to the notations of Figure 4, the tip speed ratio  $(\lambda)$  is defined as:

$$\lambda = \frac{\Omega D}{2U_0} \tag{1}$$

The mechanical torque Q and the mechanical power P output from the Savonius rotor can be defined in non-dimensional forms as:

$$C_{\mathcal{Q}} = \frac{4Q}{\rho D^2 H U_0^2} \tag{2}$$

and

$$C_P = \frac{2P}{\rho DH U_0^3} \tag{3}$$

where  $C_Q$  and  $C_P$  are the torque power coefficient and power coefficient of the Savonius rotor, respectively. The corresponding values of  $C_Q$  and  $C_P$  at each tip speed ratio ( $\lambda$ ) are used to characterize the global performance of the turbine.

In the present study, the geometry is treated in two dimensions since the blade section is simply extruded along the rotor height. However the 2D approach will neglect any 3D effects, such as those from presence of the end plates. The computational grids are generated with the trimmed cell mesher. The mesh consists of two grid components, namely, background and rotor meshes, in addition to the wake refinement that is embedded in the background mesh (see Figure 5). An overset mesh approach was applied in-between the background and the rotor meshes. The domain size is  $-10D \times 30D$  in xdirection and 10D wide in y-direction to avoid any confinement effects. Figure 5(d) shows a typical mesh around the blade with 18 prism layers next to

Fable 1. A review of unconventional black	de designs from li	iterature about Savonius rotors
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Design	Description	Gain
Dual splitters [3]	Dual splitters are introduced to the	A blade with top splitter positioned
	concave side of a Savonius rotor	at 105° succeeded in improving the
	through two approaches; top split-	performance of the Savonius rotor
	ter fixed or bottom splitter fixed	by 7.3%
Koi fish-like blade [4]	Metamodeling-based optimization	A Savonius rotor consists of two
	is applied to optimize the overlap	Koi fish-like blades with over-
	ratio and gap ratio of a Savonius	lap and gap ratios of 0.2085 and
	rotor with two blades inspired by	0.0057 exhibited about 17.6% in-
	a couple of swimming Koi fish	crease in output power coefficient
V-shaped rotor [5]	A Savonius rotor of aspect ratio	About 19.3% increase in the
	of 0.7 was developed by varying	maximum power coefficient of
	length and arc radius of 90 V-	a Savonius rotor having v-edge
	edges of the v-snaped blade profile	length and arc radius of $0.43$ and $0.56$ times the reference length re-
		spectively
Thick blade [6]	An optimization process includ-	A relative increase of 12% in out-
	ing 12 geometrical parameters was	put power coefficient has been re-
	executed to obtain a thick (non-	ported at $\lambda = 1.1$
	constant thickness) blade profile	
Different concave and convex sides	An optimization procedure was ad-	The power coefficient was in-
[7]	opted to independently modify the	creased by about 4.41% through
	convex and concave surface shapes	Particle Swarm Optimization
	of a classical Savonius rotor blade	(PSO) applied to optimize the
Multiple quarter blades [8]	A new configuration comprises	An improvement in power coeffi
Wuttiple quarter blades [8]	multiple quarter blades added to	cient ranging between 8 80% and
	the traditional configuration of a	13.69% for different inlet velocit-
	Savonius rotor	ies has been obtained by using
		multiple quarter blades
Combined blades [9]	A combination was made between	An increase up to 11% in output
[>]	semi-circular arc-shaped blade and	power coefficient can be achieved
	concave elliptical-shaped blade to	through the application of com-
	enhance the performance of a ref-	bined blades
	erence Savonius rotor.	
Airfoil-shaped blade [10]	A Savonius rotor comprises innov-	The SR3345 achieved a slight in-
	ative airfoil-shaped blades was de-	crease in $C_P$ at $\lambda < 0.5$ , while the
	veloped by modifying Goettingen	SR5050 rotor showed an enhance-
	462 and NACA 0012 airfoils, res-	ment in performance at $\lambda > 0.9$ .
	ulting in SR3345 and SR5050 air-	However, both rotors exhibited
	foils, respectively	lower $C_P$ -values than that of the
		conventional rotor at $0.5 < \lambda < 1.0$
Myring Equation-based blade [11]	A novel blade shape was de-	A Savonius rotor with a blade full-
	signed according to Myring Equa-	ness of 1 resulted in 10.98% better
	tion with the aim of increasing the	performance than a conventional
	power coefficient of the conven-	Savonius rotor
	tional Savonius rotor	

the wall. The averaged  $y^+$  is kept less than unity to capture accurately the viscous boundary layer. A mesh independence test is carried out at the design tip speed ratio ( $\lambda = 0.8$ ). The mesh density increased gradually from coarse to fine by a refinement ratio of about 1.3. Following three mesh refinements, a difference of less than 1% is obtained. The total number of cells employed is about 200k. The simulation requires about 24h to complete 20 revolutions on two parallel nodes of the HPC-Cluster at "Otto von Guer-icke" University Magdeburg.

The commercial software Simcenter STAR-CCM+ 2021.3 is used for the solution of the unsteady Reynolds-averaged Navier-Stokes (URANS) equations. The  $k - \omega$  Shear-Stress-Transport (SST) turbulence model by Menter [13] was applied. This



Figure 3. Various models of sand eel-like blades with different values of maximum camber  $(f_{max})$  and maximum camber location  $(X_{f_{max}})$  at  $t_{max} = 20\% f_{max}$ 

Table 2.	Specifications	of the	Savonius	rotor	with
semi-ciro	cular arc blade	es [12]			

Parameter	Value
Rotor diamater D	0.33 m
Rotor height H	0.23 m
Rotor overlap C	0.066 m
Blade diamater d	0.184 m
Shaft diamater a	0.015 m

model delivers efficient predictions for flows involving strong adverse pressure gradients. Doubleprecision accuracy of floating point numbers and second-order discretization in space and time is applied. The governing equations are solved using a segregated flow solver. Three different timestep sizes corresponding to azimuth angles of  $2^{\circ}$ ,  $1^{\circ}$  and  $0.5^{\circ}$ were investigated. According to the results of a timeindependent analysis, a timestep size of  $0.5^{\circ}$  is found necessary for the present numerical simulations.

The number of revolutions plays a critical role in obtaining a converged solution for numerical simulations of turbomachinery. To maintain reasonable computational time, each numerical simulation was allowed to run for 20 revolutions to ensure that the average torque coefficient ( $C_Q$ ) shows periodicity in time. After 20 revolutions (t = 4.32 s), the average



Figure 4. Geometry of the standard Savonius rotor

torque coefficient  $(C_Q)$  does not show any significant changes over time (variations below 0.003). The average torque coefficient  $(C_Q)$  has always been calculated by time-averaging the values over the last five revolutions.

## 4. RESULTS AND DISCUSSION

The full numerical procedure has been validated with published numerical results [14] and experimental measurements [12] based on a standard Savonius rotor. The present numerical results match very well with numerical results of Mohamed et al. (2011), both using the  $k - \omega$  SST turbulence model (see Figure 6). However, there is a significant deviation compared to the experimental measurements that can be attributed to the 2D assumption. It is worth mentioning that the presence of endplates in the experiment conducted by Hayashi et al. [12] is not taken into account in the present study.

As can be noticed from Figure 6(b), the maximum deviation between the present numerical 2D results and experimental measurements for  $C_P$  is about 37.30%. A comparable deviation has been reported by Mohamed et al. [14] and Hosseini Imeni et al. [15] as 36.45% and 25.44%, respectively; all these studies involve 2D numerical simulations with the  $k - \omega$  SST model. In other words, the  $k - \omega$ SST model usually overpredicts the performance of Savonius rotors when the problem is modeled as twodimensional or planar. To support this statement, the maximum deviation between the numerical results and experimental measurements is reduced to be only 12.22% when a 3D numerical simulation is carried out, as reported by Elmekawy et al. [16].



Figure 6. A comparison of the predicted (a) torque coefficient  $(C_Q)$  and (b) power coefficient  $(C_P)$  to published numerical results [14] and experimental measurements [12]

Before starting the parametric study, two different arrangements of sand eel-like blades were examined at the design tip speed ratio ( $\lambda = 0.8$ ), one when the fish head is facing outward and the other when the fish head is facing inward with respect to the rotor axis. This preliminary study showed that the output power coefficient ( $C_P$ ) is higher when the fish head is facing inward compared to the other arrangement. Therefore, only one arrangement (fish head facing inward) is considered in the parametric study (see Figure 5).

Figure 7 represents a scatter plot for the calculated power coefficient  $(C_P)$  of sand eel-like blades with different maximum camber  $(f_{max}/d)$  and maximum camber location  $(X_{f_{max}}/d)$  values at  $\lambda = 0.8$ . The highest performance could be achieved with



Figure 5. Computational mesh for a Savonius rotor with sand eel-like blades: background (a), wake refinement (b), rotor (c) and blade (d). The boundary conditions are described by the blue-coloured text

high cambered sand-eel like blades, particularly at camber locations  $(X_{f_{max}}/d)$  of 0.5 and 0.8. On the other hand, sand eel-like blades with low camber and camber location values deliver the worst performance for the Savonius wind turbine. From the simulations, the output power coefficient  $(C_P)$  has been calculated for 54 sand eel-like blades. In this manner, the best and the worst blade designs could thus easily be distinguished for  $\lambda = 0.8$ . Therefore, the best blade design corresponds to  $f_{max}/d = 0.4$  and  $X_{f_{max}}/d$ = 0.8 with  $C_P$  = 0.2486 whereas a blade design with  $f_{max}/d=0.1$  and  $X_{f_{max}}/d=0.1$  exhibited the lowest power coefficient ( $C_P = 0.0581$ ), as presented in Figure 7. For the best-performing sand eel-like blade  $(f_{max}/d = 0.4 \text{ and } X_{f_{max}}/d = 0.8)$ , this gain leads to an improvement in turbine performance of about 8.3% at the design tip speed ratio ( $\lambda = 0.8$ ), compared to a Savonius wind turbine with semi-circular arc blades.

Figure 8 shows the streamlines around the standard Savonius wind turbine with semi-circular arc blades (a) and that with the best-performing sand eellike blades (b) at  $\lambda = 0.8$ . For both rotors, a separation vortex can be observed on the convex side located near the leading edge (fish head) of the advancing blade (blade A). However, the separation vortex is less intensive for the sand eel-like blade. It can be noticed that the stagnation point on the surface of the returning blade (blade R) of the sand eellike blade is shifted to occur near the trailing edge (fish tail) whereas it occurs nearly at middle of the semi-circular arc blade. The flow through the gap between the blades is more pronounced in case of the Savonius rotor with sand eel-like blade compared to the standard rotor.

The pressure distributions at  $\lambda = 0.8$  are shown in Figure 9. The deep differences in the pressure distributions between the two rotors due to different blade designs are obvious. The sand eel profile experiences considerably higher pressure on the concave surface of the advancing blade (blade A) compared to the semi-circular arc. Moreover, the pressure is relatively lower on the convex side of the sand eel-like blade than for the semi-circular blade. The larger pressure difference between both sides of the sand eel-like blades produces a higher force, explaining the better performance.

#### 5. CONCLUSIONS

The present study investigated the performance of a Savonius wind turbine with unconventional



Figure 7. Scatter plot for different maximum camber  $(f_{max}/d)$  and maximum camber location  $(X_{f_{max}}/d)$  values colored by power coefficient  $(C_P)$  of the Savonius rotor with sand eel-like blades at  $\lambda = 0.8$ 



Figure 8. Streamlines around Savonius rotor with semi-circular arc blades (a) and that with the best-performing sand eel-like blades (b) at  $\lambda = 0.8$ 

blade designs inspired biologically by sand eels. A total of 54 sand eel-like blades are obtained by changing the camber and camber location of bio-inspired blades that fitted into a Savonius rotor. The new bioinspired blade designs were evaluated by means of 2D numerical simulations to assess the performance in terms of output power coefficient ( $C_P$ ). The parametric study identifies a better Savonius rotor than the standard one with semi-circular blades, leading



Figure 9. Pressure distributions of Savonius rotor with semi-circular arc blades (a) and that with the best-performing sand eel-like blades (b) at  $\lambda = 0.8$ 

to an improvement in performance by 8.3% at the design tip speed ratio ( $\lambda = 0.8$ ). Analyzing the flow field around both Savonius rotors explains this superior performance.

In this study, the best-performing bio-inspired blade has been obtained manually out of 54 designs.

It might not be the optimal one. Accordingly, the next step could involve a systematic optimization procedure to reach the optimal sand eel-like blade. Furthermore, in the present parametric study, the sand eel-like blades were evaluated only at the design tip speed ratio ( $\lambda = 0.8$ ). However, the new blade should also be tested at off-design conditions (several  $\lambda$ -values) to check how the gain changes through the full operating range.

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